

Image Processing

Spatial Transforms

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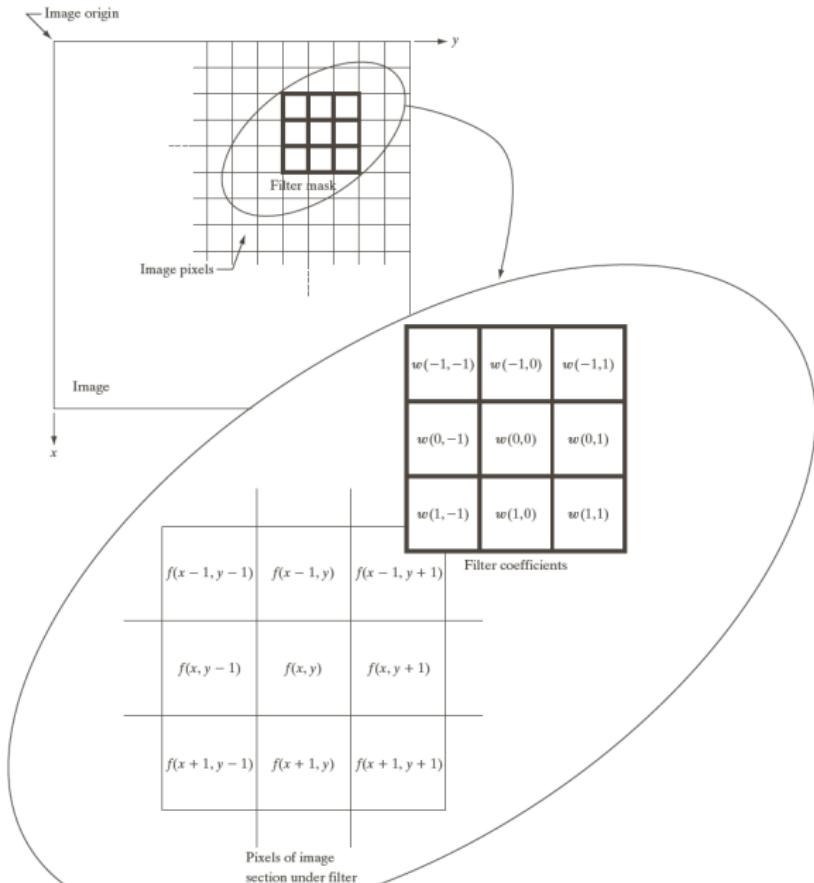
15 de Março de 2017

Class 04:



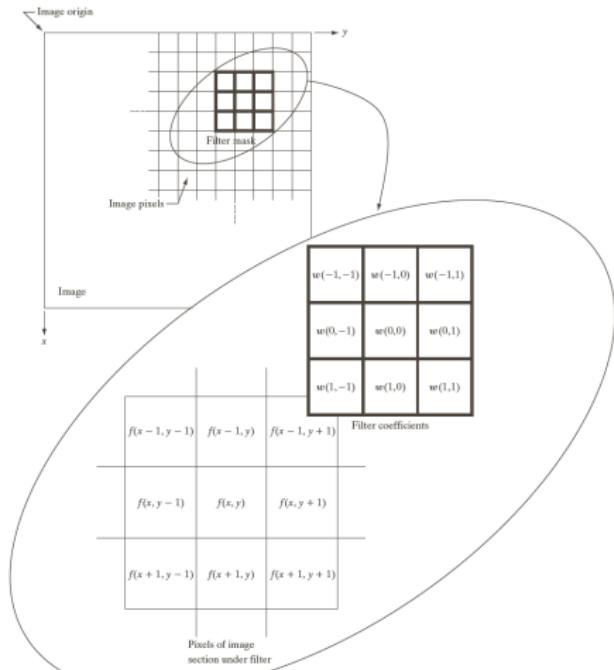
- Spatial Filtering

Spatial Filtering



Spatial Filtering

$$g(x, y) = \sum_{s=-a}^a \sum_{t=-b}^b w(s, t) f(x + s, y + t)$$



Spatial Filtering

$$R = w(-1, -1)f(x-1, y-1) + w(-1, 0)f(x-1, y) + \dots \\ + w(0, 0)f(x, y) + \dots + w(1, 0)f(x+1, y0) + w(1, 1)f(x+1, y+1)$$

w_1	w_2	w_3
w_4	w_5	w_6
w_7	w_8	w_9

$$R = w_1z_1 + w_2z_2 + \dots w_mnz_mn \\ = \sum_{i=1}^{mn} w_i z_i$$

Spatial Filtering

Correlation

(a)
Origin f w
0 0 0 1 0 0 0 0 1 2 3 2 8

(b)
Origin f w
0 0 0 1 0 0 0 0 1 2 3 2 8
Starting position alignment

(c)
Origin f w
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
1 2 3 2 8
Zero padding

(d)
Origin f w
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
1 2 3 2 8
Position after one shift

(e)
Origin f w
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
1 2 3 2 8
Position after four shifts

(f)
Origin f w
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
1 2 3 2 8
Final position

(g)
Full correlation result
0 0 0 8 2 3 2 1 0 0 0 0

(h)
Cropped correlation result
0 8 2 3 2 1 0 0

Convolution

(i)
Origin f w rotated 180°
0 0 0 1 0 0 0 0 8 2 3 2 1

(j)
Origin f w rotated 180°
0 0 0 1 0 0 0 0 8 2 3 2 1

(k)
Origin f w rotated 180°
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
8 2 3 2 1

(l)
Origin f w rotated 180°
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
8 2 3 2 1

(m)
Origin f w rotated 180°
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
8 2 3 2 1

(n)
Origin f w rotated 180°
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
8 2 3 2 1

(o)
Full convolution result
0 0 0 1 2 3 2 8 0 0 0 0

(p)
Cropped convolution result
0 1 2 3 2 8 0 0

Spatial Filtering

Spatial Filtering

$$R = w(-1, -1)f(x-1, y-1) + w(-1, 0)f(x-1, y) + \dots \\ + w(0, 0)f(x, y) + \dots + w(1, 0)f(x+1, y0) + w(1, 1)f(x+1, y+1)$$

w_1	w_2	w_3
w_4	w_5	w_6
w_7	w_8	w_9

$$R = w_1z_1 + w_2z_2 + \dots w_mnz_mn \\ = \sum_{i=1}^{mn} w_i z_i$$

Spatial Filtering

$$\frac{1}{9} \times \begin{array}{|c|c|c|} \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline 1 & 1 & 1 \\ \hline \end{array} \quad \frac{1}{16} \times \begin{array}{|c|c|c|} \hline 1 & 2 & 1 \\ \hline 2 & 4 & 2 \\ \hline 1 & 2 & 1 \\ \hline \end{array}$$

$$R = \frac{1}{9} \sum_{i=1}^{mn} z_i$$

ou, genericamente:

$$R = \frac{\sum_{s=-a}^a \sum_{t=-b}^b w(s, t) f(x + s, y + t)}{\sum_{s=-a}^a \sum_{t=-b}^b w(s, t)}$$

Eliminating Details



Filters: $m = 3, 5, 9, 15$, e 35 .

Eliminating Details

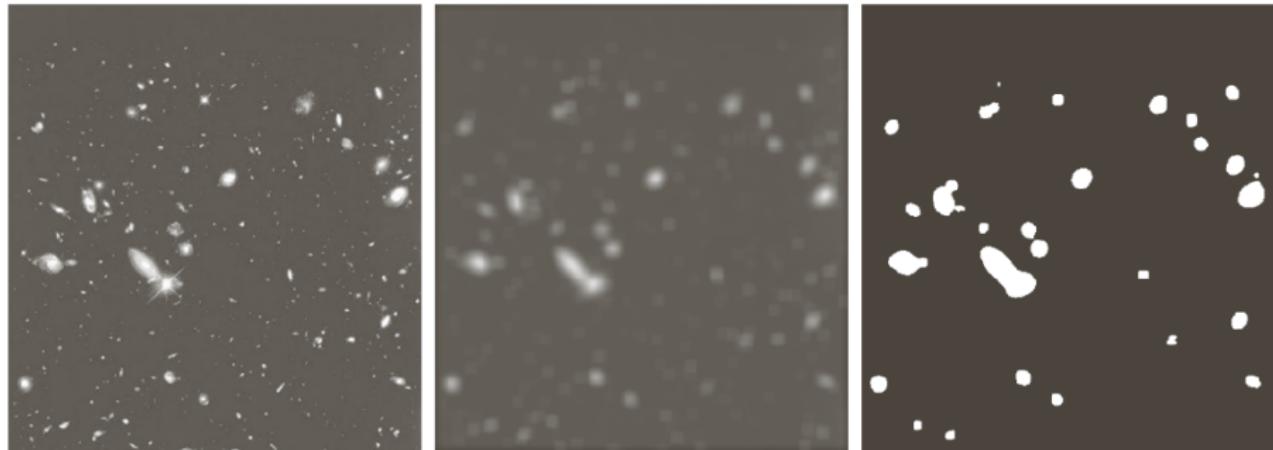
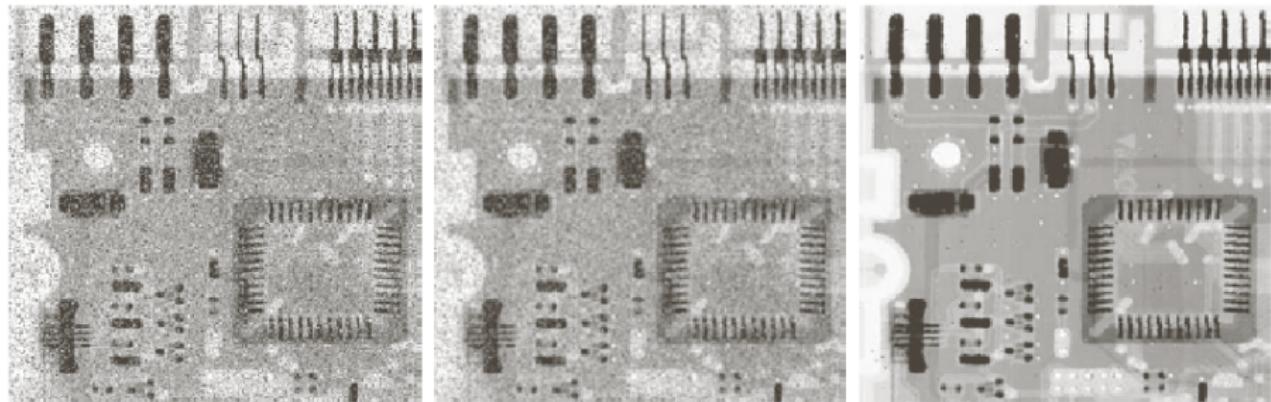


Image with 528×485 pixels. Filter with a 15×15 filter, followed by a thresholding operation.

- Median:
 - Eliminates the pixels whose properties differ from the properties of the neighboring pixels;
 - Isolated Areas ($< m^2/2$ of the neighborhood) are eliminated;
 - Salt and paper
- Max, Min, percentile, etc.



a b c

FIGURE 3.35 (a) X-ray image of circuit board corrupted by salt-and-pepper noise. (b) Noise reduction with a 3×3 averaging mask. (c) Noise reduction with a 3×3 median filter. (Original image courtesy of Mr. Joseph E. Pascente, Lixi, Inc.)

Sharpening Spatial Filters

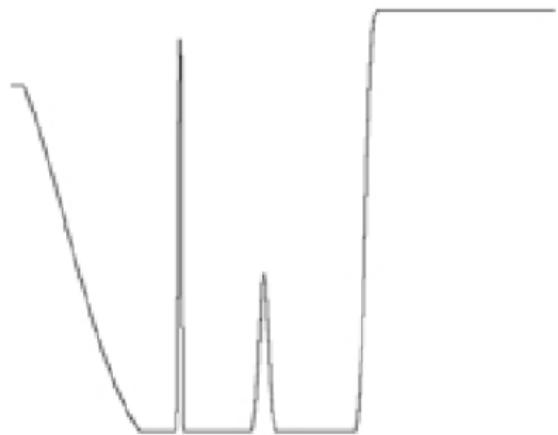
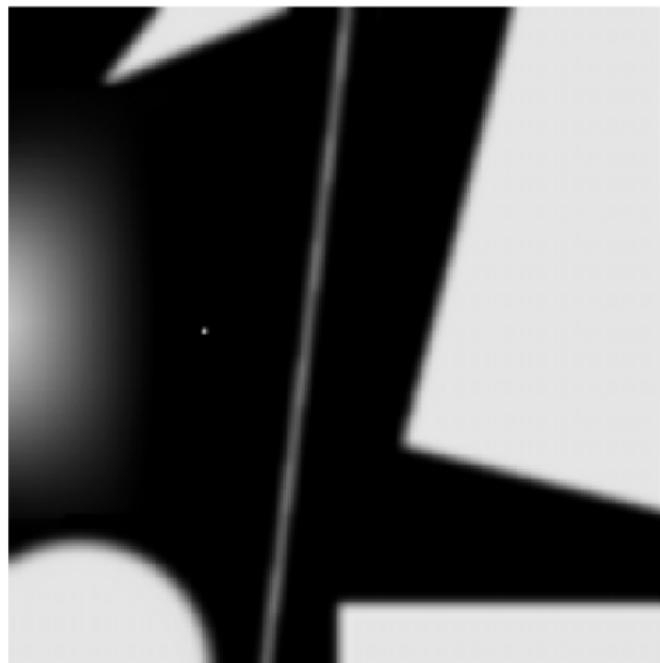
- 1st order derivative (discrete)

$$\frac{\partial f}{\partial x} = f(x + 1) - f(x)$$

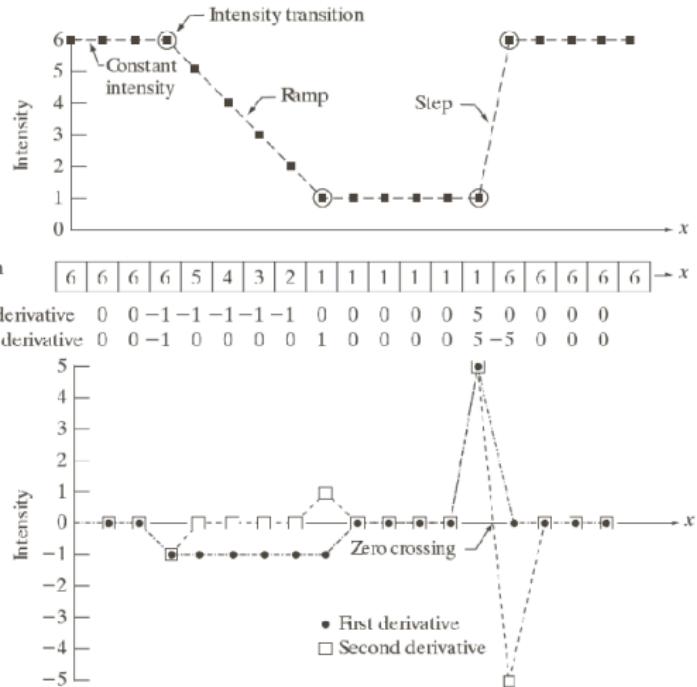
- 2nd Order derivative (discrete)

$$\frac{\partial^2 f}{\partial x^2} = f(x + 1) + f(x - 1) - 2f(x)$$

Sharpening Spatial Filters



Sharpening Spatial Filters



Laplacian Filters

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$$

onde

$$\frac{\partial^2 f}{\partial x^2} = f(x+1, y) + f(x-1, y) - 2f(x, y)$$

e

$$\frac{\partial^2 f}{\partial y^2} = f(x, y+1) + f(x, y-1) - 2f(x, y)$$

Logo

$$\boxed{\nabla^2 f = [f(x+1, y) + f(x-1, y) + f(x, y+1) + f(x, y-1)] - 4f(x, y)}$$

Laplacian Filters

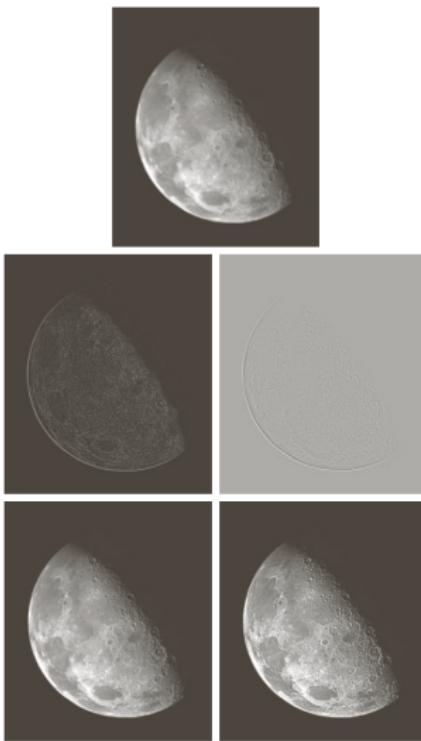
0	1	0
1	-4	1
0	1	0

1	1	1
1	-8	1
1	1	1

0	-1	0
-1	4	-1
0	-1	0

-1	-1	-1
-1	8	-1
-1	-1	-1

Laplacian Filters



(a) blurred image, (b) Laplacian (no scaling), (c) Laplacian (scaling), (d)
Original image + (a), (d) Original image + (b)

Unsharp Masking

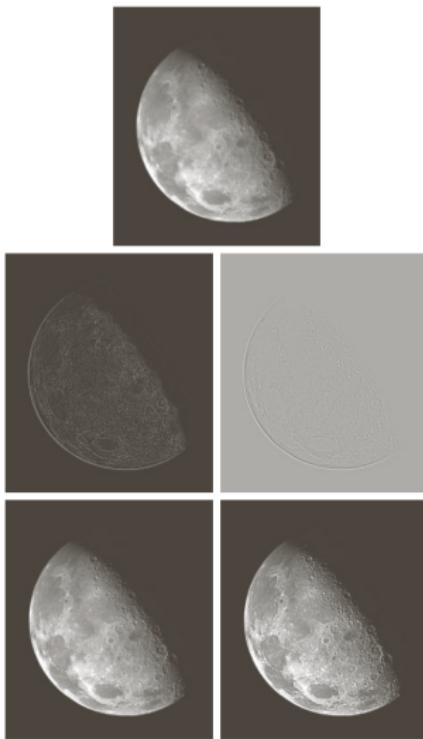
Steps:

① $\bar{f}(x, y) = \text{conv}(h_{LP}(x, y), f(x, y)) = h_{LP}(x, y) * f(x, y)$

② $g_{mask} = f(x, y) - \bar{f}(x, y)$

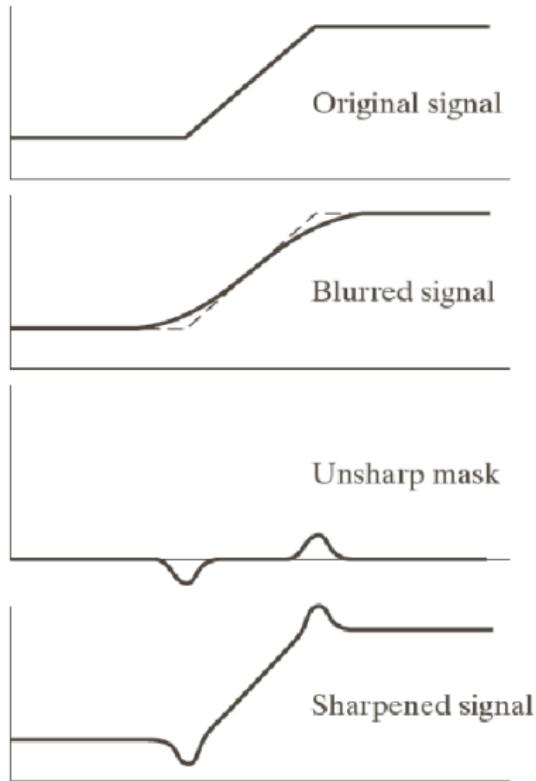
③ $g(x, y) = f(x, y) + k \cdot g_{mask}(x, y)$

Unsharp Masking



(d) Unsharp masking.

Unsharp Masking



High Boost

PSteps:

$$f_{hb}(x, y) = Af(x, y) - \bar{f}(x, y)$$

$$f_{hb}(x, y) = (A - 1)f(x, y) + f(x, y) - \bar{f}(x, y)$$

$$f_{hb}(x, y) = (A - 1)f(x, y) - f_s(x, y)$$

0	-1	0	-1	-1	-1
-1	$A + 4$	-1	-1	$A + 8$	-1
0	-1	0	-1	-1	-1

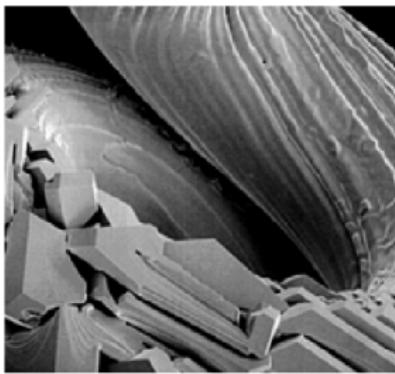
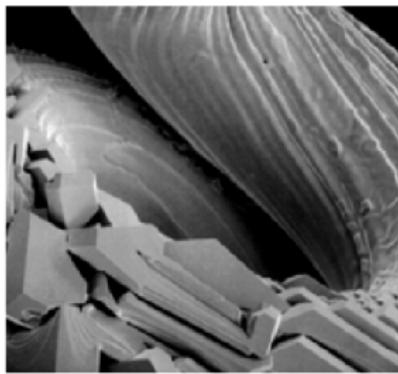
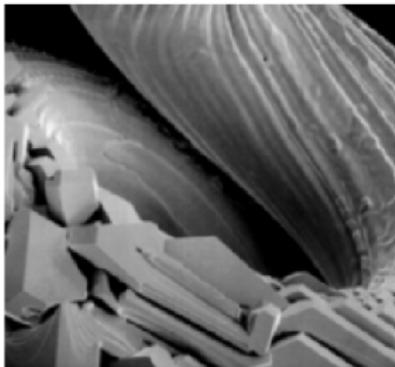


original, borrado com Gaussiano, unsharp mask, resultado do unsharp mask, resultado do high-boost

High Boost

0	-1	0
-1	5	-1
0	-1	0

-1	-1	-1
-1	9	-1
-1	-1	-1



a b c
d e

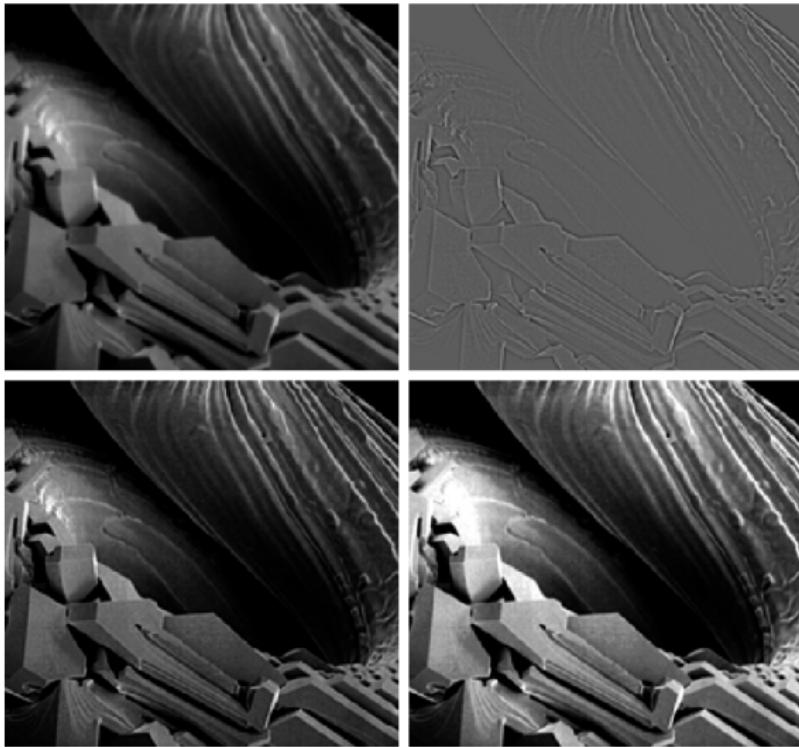
FIGURE 3.41 (a) Composite Laplacian mask. (b) A second composite mask. (c) Scanning electron microscope image. (d) and (e) Results of filtering with the masks in (a) and (b), respectively. Note how much sharper (e) is than (d). (Original image courtesy of Mr. Michael Shaffer, Department of Geological Sciences, University of Oregon, Eugene.)

High Boost

a
b
c
d

FIGURE 3.43

- (a) Same as Fig. 3.41(c), but darker.
(a) Laplacian of (a) computed with the mask in Fig. 3.42(b) using $A = 0$.
(c) Laplacian enhanced image using the mask in Fig. 3.42(b) with $A = 1$. (d) Same as (c), but using $A = 1.7$.



1st Order Derivative

Passos:

$$\nabla f = \begin{vmatrix} G_x \\ G_y \end{vmatrix} = \begin{vmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{vmatrix}$$

$$\begin{aligned}\nabla f &= \text{mag}(\nabla f) \\ &= [G_x^2 + G_y^2]^{1/2} \\ &= \left[\frac{\partial f^2}{\partial x} + \frac{\partial f^2}{\partial y} \right]^{1/2}\end{aligned}$$

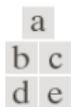
OR

$$\nabla f \approx |G_x| + |G_y|$$

z_1	z_2	z_3
z_4	z_5	z_6
z_7	z_8	z_9

-1	0	0	-1
0	1	1	0
-1	-2	-1	-1
0	0	0	-2

1	2	1	-1	0	1
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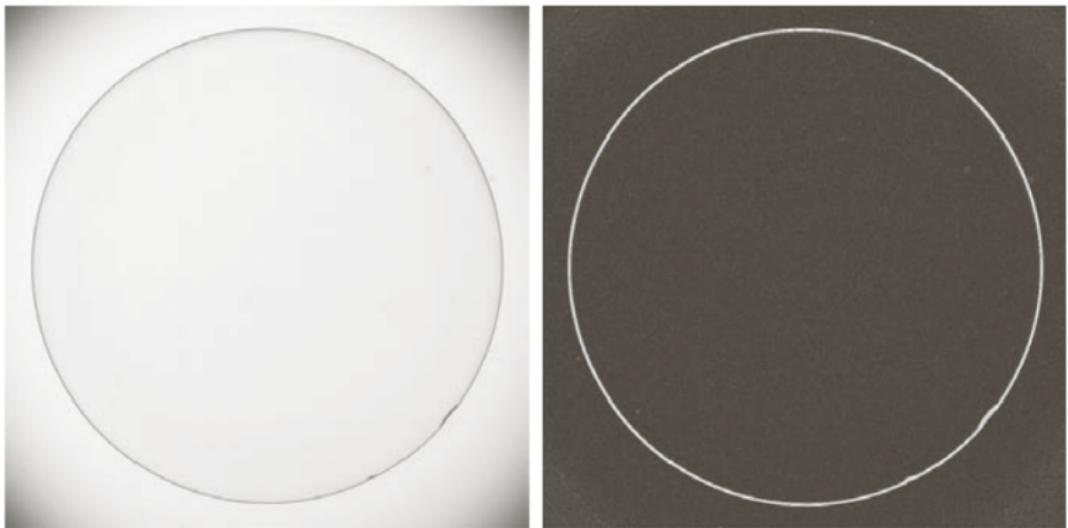
**FIGURE 3.41**

A 3×3 region of an image (the z s are intensity values).

(b)–(c) Roberts cross gradient operators.

(d)–(e) Sobel operators. All the mask coefficients sum to zero, as expected of a derivative operator.

Roberts & Sobel



Original & Sobel

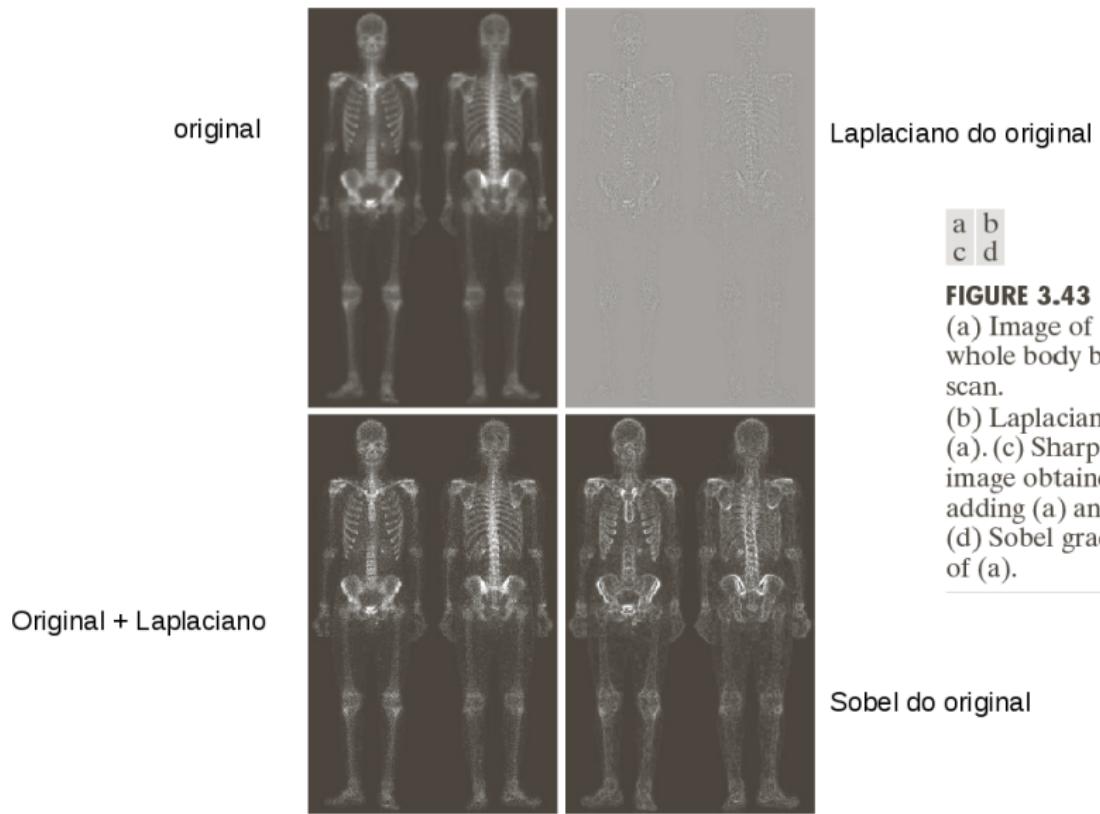


FIGURE 3.43

(a) Image of whole body bone scan.
(b) Laplacian of (a). (c) Sharpened image obtained by adding (a) and (b).
(d) Sobel gradient of (a).